CS 573: Graduate Algorithms, Fall 2010 Homework 5

Practice only — Do not submit solutions

1. (a) Describe how to transform any linear program written in general form into an equivalent linear program written in *slack* form.

- (b) Describe precisely how to dualize a linear program written in slack form.
- (c) Describe precisely how to dualize a linear program written in general form.

In all cases, keep the number of variables in the resulting linear program as small as possible.

- 2. Suppose you have a subroutine that can solve linear programs in polynomial time, but only if they are both feasible and bounded. Describe an algorithm that solves arbitrary linear programs in polynomial time. Your algorithm should return an optimal solution if one exists; if no optimum exists, your algorithm should report that the input instance is Unbounded or Infeasible, whichever is appropriate. [Hint: Add one variable and one constraint.]
- 3. An integer program is a linear program with the additional constraint that the variables must take only integer values.
 - (a) Prove that deciding whether an integer program has a feasible solution is NP-complete.
 - (b) Prove that finding the optimal feasible solution to an integer program is NP-hard.

[Hint: Almost any NP-hard decision problem can be formulated as an integer program. Pick your favorite.]

4. Give a linear-programming formulation of the minimum-cost feasible circulation problem. You are given a flow network whose edges have both capacities and costs, and your goal is to find a feasible circulation (flow with value 0) whose cost is as small as possible.

5. Given points $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ in the plane, the *linear regression problem* asks for real numbers a and b such that the line y = ax + b fits the points as closely as possible, according to some criterion. The most common fit criterion is minimizing the L_2 error, defined as follows:¹

$$\varepsilon_2(a,b) = \sum_{i=1}^n (y_i - ax_i - b)^2.$$

But there are several other fit criteria, some of which can be optimized via linear programming.

(a) The L_1 error (or total absolute deviation) of the line y = ax + b is defined as follows:

$$\varepsilon_1(a,b) = \sum_{i=1}^n |y_i - ax_i - b|.$$

Describe a linear program whose solution (a, b) describes the line with minimum L_1 error.

(b) The L_{∞} error (or maximum absolute deviation) of the line y = ax + b is defined as follows:

$$\varepsilon_{\infty}(a,b) = \max_{i=1}^{n} |y_i - ax_i - b|.$$

Describe a linear program whose solution (a, b) describes the line with minimum L_{∞} error.

¹This measure is also known as *sum of squared residuals*, and the algorithm to compute the best fit is normally called *(ordinary/linear) least squares fitting.*